## Reliable and Energy-Efficient Data Delivery in Sparse WSNs with Multiple Mobile Sinks

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Based on joint work with

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### Overview



- WSNs with Mobile Sinks
  - Advantages and Challenges
- Reliable & Energy Efficient Data Delivery to MSs
  - Adaptive Hybrid Protocol
- Simulation Results
- Experimental Measurements
- Conclusions



## WSNs with Mobile Sinks



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### **Advantages**

- Connectivity
  - A sparse sensor network may be a feasible solution for a large number of applications.
- Cost
  - Reduced number of sensor nodes → reduced costs
- Reliability
  - Single-hop communication instead of multi-hop communication
  - Reduced contentions/collisions and message losses
- Energy Efficiency
  - Mobile Sinks can help reducing the funneling effect



## Approaches to Data Collection





## Reliable and Energy-efficient Data Delivery to Mobile Sinks

Which is the best way to transfer *all* the data available at the sensor node to the Mobile Sink(s) with the minimum energy expenditure?

### **Reference Scenario**



- Urban Sensing Scenario
  - Sparse WSN with multiple mobile users
  - Each user consumes data for its own purposes (MS)
  - Bundle-oriented communication





- Challenges
  - Contacts are sporadic and short
    - ⇒ Contact duration depends on MS path, speed, ...
  - Some contacts may be missed due to duty cycle





- Challenges
  - The discovery phase further reduces the residual contact time





### Challenges

- Communication is impaired by message losses
- This reduces the available bandwidth





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### Challenges

- Multiple MSs simultaneously in contact
  - ⇒ They typically enter the contact area at different times
  - ⇒ They have different contact durations
  - ⇒ Tthey experience different conditions (e.g., message loss)



## **Data Transfer Protocol**



- Design Principles
  - Reliable communication despite of message losses
  - Efficient exploitation of limited resources
    - ⇒ Verbose protocols should be avoided
  - Adaptation to channel conditions
    - ⇒ Non accurate information
    - ⇒ Time-varying channel conditions
    - → Multiple MSs
  - Beaconing is required also during communication
    - ⇒ This can be achieved through ACKs

### **Common Approach**



### ARQ Scheme

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## **Selective Repeat**

### Simple ARQ Scheme

- The sender transmits data messages
- The receiver replies with ACKs including an indication of data messages correctly received
- Selective retransmission of missed/corrupted messages

### Robust against message losses

- Corrupted or missed messages are retransmitted
- No assumption about the MS's location

### Suitable for unicast communication

Data are to be transferred to a single MS at a time

## Erasure coding





Any subset of *k* encoded blocks allows the receiver to reconstruct the source data

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### Which is the optimal redundancy?



The source node sends (k + R) codes.

Which is the probability to receive correctly at least k codes at the destination?

$$P_{succ} = \Pr{ob\{k' \ge k\}} = \sum_{i=k}^{k+R} \binom{k+R}{i} \cdot p^i \cdot (1-p)^{k+r-i}$$

where:

k': number of codes correctly received by the destination

p: packet loss (constant)

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## Energy Efficiency



$$\eta = \frac{k \cdot S_{MSG}}{(k+R) \cdot \delta_{MSG} \cdot P_{tx}} \cdot P_{succ}$$

#### where:

 $P_{succ}$ probability to receive at least k codeskoriginal number of messages $S_{MSG}$ message size (in bytes)k + Rtotal number of coded messages sent $\delta_{MSG}$ time taken to send a single coded message $P_{tx}$ transmit power

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MS3

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### Multiple MS scenario

- The required redundancy is different for different MSs
- For a given MS, the required redundancy varies over time

Redundancy should be adaptive

 Contact

 area

 Rx

 Sensor node

ACKs are required for implicit beaconing

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### Hybrid Approach

### HI: <u>Hybrid</u> Interleaved Data Delivery

- Adaptive Erasure Coding + ACKs
- Reed-Solomon codes are considered



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### **Basic idea**



- The bundle is divided in B blocks
- Each block is then encoded separately
- Codes are generated in advance...
- ... and sent out on demand
- The number of transmitted codes depends on feedbacks received from MSs (through ACKs)

## Interleaved Transmission



- HI: Hybrid Interleaved Data Delivery
  - Messages to transmit are picked from consecutive blocks
  - Uniform distribution of message losses among blocks





### Simulation Setup

- Ad Hoc Simulator
  - HI Protocol and SR Protocol
  - Discovery based on periodic beaconing emission by MSs
- Scenario
  - Single Sensor, Multiple MSs
  - MSs move along linear paths, at a fixed distance from the sensor
- Message Losses



		2	1	>
$p(t) = a_2$	$\left(t-\frac{c_{\max}}{2}\right)$	$+a_{1}$	$\left(t-\frac{c_{\max}}{2}\right)$	$\left(\frac{1}{2}\right) + a_0$

Parameter	v=3.6 km/h	v=20 km/h	<i>v</i> =40 km/h
c <sub>max</sub>	158s	30s	17s
a <sub>0</sub>	0.133	0.3828	0.4492
a <sub>1</sub>	0 s <sup>-1</sup>	0 s <sup>-1</sup>	0 s <sup>-1</sup>
a <sub>2</sub>	0.000138 s <sup>-2</sup>	0.0028 s <sup>-2</sup>	0.0077 s <sup>-2</sup>

G. Anastasi, M. Conti, E. Monaldi, A. Passarella, An Adaptive Data-transfer Protocol for Sensor Networks with Data Mules, *Proc. IEEE WoWMoM* 2007, Helsinki, Finland, June 18-21, 2007.

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## **Performance Metrics**



### Decoding Probability

- probability of receiving the minimum amount of codes for a MS being able to decode the original data bundle
- in the SR protocol, probability of receiving the complete bundle

### Energy Consumption

 average total energy consumed by the sensor node per each byte correctly transferred to MS(s)



## **Simulation Parameters**



Parameter		Value
k, n (HI protocol)		8, 256
Message/ACK Size		110 bytes
Message Transmission Time $\delta_{_{\!M\!S\!G}}$		17 ms
ACK Transmission Time	$\delta_{\scriptscriptstyle ACK}$	17 ms
ACK Period	T <sub>ACK</sub>	16* <i>δ</i> <sub>АСК</sub>
Beacon Period	$T_B$	100 ms
N <sub>ACK</sub> (40Km/h, 3.6Km/h)		8, 24
Duty Cycle ( <i>D</i> )		5%
Transmission Power	$P_{tx}$	52.2 mW
Reception Power	$P_{rx}$	56.4 mW

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## Validation with real sensor nodes



- T-mote Sky
  - TinyOS Operating System
  - IEEE 802.15.4 PHY
  - Mobility and message loss

$$p(t) = a_2 \left( t - \frac{c_{\text{max}}}{2} \right)^2 + a_1 \left( t - \frac{c_{\text{max}}}{2} \right) + a_0$$



### Experimental vs. Simulation Results





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## **Energy Cost of Coding**



- Coding/decoding consumes energy
  - Decoding is not an issue as MSs are resource rich
  - Coding may be an issue
- Energy Consumption for coding
  - CPU Power consumption: 3 mW
  - 256-code blocks  $\rightarrow$  40.5  $\mu$ J/byte
  - Larger than the energy consumed for transmission
    - $\Rightarrow$  ~30  $\mu$ J/byte (with 1 MS)

## Memory requirements



- Memory Requirements
  - 256-code block (8+248) = 256\*110 bytes = 28 KB
- Memory Availability
  - Tmote Sky: 32 KB
  - Jennic: 96 KB
  - SunSpot: 512 KB

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### Impact of Redundancy





### **Resource Requirements**



- Energy Consumption for coding
  - 256 codes → 40.5 µJ/byte
  - 32 codes  $\rightarrow$  3.9  $\mu$ J/byte
    - $\Rightarrow$  Negligible wrt energy spent for transmission (~30 µJ/byte with 1 MS)
- Memory Requirements
  - 256-code block (8+248) = 256\*110 bytes = 28 KB
  - 32-code block (8+24) = 32\*110 bytes = 3.5 KB
- Memory Availability
  - Tmote Sky: 32 KB
  - Jennic: 96 KB
  - SunSpot: 512 KB

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### Conclusions



- Reliable & Energy Efficient Data Transfer in Sparse WSNs with Multiple MSs
  - Sporadic and short contact times
  - Communication affected by message losses
- HI protocol
  - Erasure Coding + ACKs
  - Coding is performed in advance
  - Number of transmitted codes depends on loss conditions
- Simulation + Experimental Evaluation
  - HI outperforms SR even when there is a single MS
  - Energy for coding is negligible wrt energy for transmission

### References



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# Thank you!

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